

On a rod motion in a rarefied particle medium

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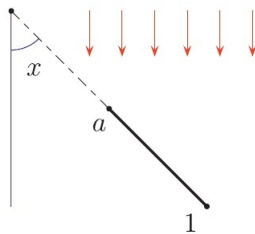
The eighty-fifth Anniversary of Adyghe State University, 10 October 2025

Flight of rod



Rod in plane rarefied flow

Team work with Alexander Plakhov.



$2(v \sin x + r\dot{x})$ – velocity change of particle reflected at $r \in [a, 1]$;

$\rho|v \sin x + r\dot{x}|drdt$ – mass of particles reflected from a segment $[r, r + dr]$ during dt ;

$2\rho \int_a^1 (v \sin x + r\dot{x})|v \sin x + r\dot{x}| r dr$ – moment of force acting on the rod.

Equation of pendulum dynamic is

$$I\ddot{x} = -2\rho \int_a^1 (v \sin x + r\dot{x})|v \sin x + r\dot{x}| r dr.$$

Four regions of different rod dynamics: equations

Make the change of variable $\tau = vt$ and introduce k , $k = 2\rho/l$:

$$\ddot{x} = k \int_a^1 (\sin x + r\dot{x}) |\sin x + r\dot{x}| r dr.$$

(a) $\sin x + r\dot{x} \geq 0$ for all $r \in [a, 1]$ or $\dot{x} \geq \max \left\{ -\sin x, -\frac{\sin x}{a} \right\}$;

$$\ddot{x} = -k \left[\frac{1-a^2}{2} \sin^2 x + 2 \frac{1-a^3}{3} \dot{x} \sin x + \frac{1-a^4}{4} \dot{x}^2 \right].$$

(b) $\sin x + a\dot{x} \geq 0$ and $\sin x + \dot{x} < 0$, or $-\frac{\sin x}{a} \leq \dot{x} < -\sin x$:

$$\ddot{x} = k \left\{ \left[\frac{1+a^2}{2} \sin^2 x + 2 \frac{1+a^3}{3} \dot{x} \sin x + \frac{1+a^4}{4} \dot{x}^2 \right] - \frac{\sin^4 x}{6\dot{x}^2} \right\}.$$

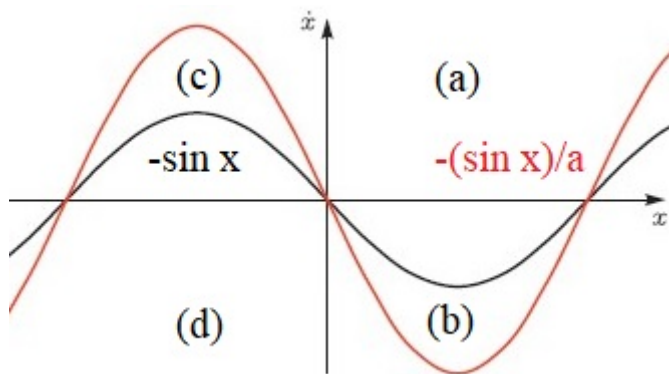
(c) $\sin x + a\dot{x} < 0$ and $\sin x + \dot{x} \geq 0$, or $-\sin x \leq \dot{x} < -\frac{\sin x}{a}$.

(d) $\sin x + r\dot{x} < 0$ for all $r \in [a, 1]$, or $\dot{x} < \min \left\{ -\sin x, -\frac{\sin x}{a} \right\}$:

(c) $\ddot{x} = -$ case(b)

(d) $\ddot{x} = -$ case(b)

Four regions of different rod dynamics



Singular points I

With $y := \dot{x}$ we have

$$\dot{x} = y \quad \text{and} \quad \dot{y} = v(x, y)$$

where $x(x, y)$ is the respective expression in the domains (a)-(d). Singular points are $(0, 0)$, $(\pi, 0)$ up to x -period 2π . For the part of (d) with $\pi \leq x \leq \pi + \epsilon$ introduce $z > 0$, w with $x = \pi + z^2$ and $y = wz^3$. That gives $\dot{z} = wz^2/2$ and

$$\dot{w} = k \left\{ -\frac{3}{2} w^2 z + \frac{1 - a^2}{2} \frac{\sin^2 z^2}{z^3} + 2 \frac{1 - a^3}{3} w \sin z^2 + \frac{1 - a^4}{4} w^2 z^3 \right\}.$$

After the division the vector field by $z > 0$ we get $\dot{z} = wz/2$ and

$$\dot{w} = k \left\{ -\frac{3}{2} w^2 + \frac{1 - a^2}{2} \frac{\sin^2 z^2}{z^4} + 2 \frac{1 - a^3}{3} \frac{\sin z^2}{z^2} wz + \frac{1 - a^4}{4} w^2 z^2 \right\}$$

Singular points II

$$z_0 = 0, \quad w_0 = w_{\pm} \quad \text{with} \quad w_{\pm} = \pm \sqrt{\frac{1-a^2}{3}}.$$

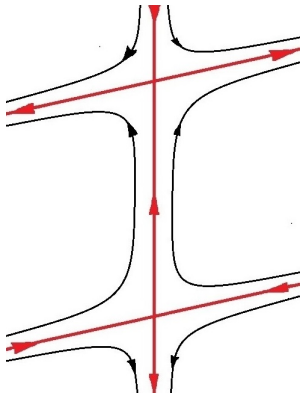
The matrix of linearization of the field at these points is

$$\begin{pmatrix} w_0/2 & 0 \\ 2\frac{1-a^3}{3}kw_0 & -3kw_0 \end{pmatrix}. \quad (1)$$

Its eigenvalues $w_0/2$ and $-3kw_0$ are real and have different signs, hence the points are non-degenerate saddles. The corresponding eigendirections are $(18k+3, 4k(1-a^3))$ and $(0, 1)$.

Singular point $(\pi, 0)$ I

In the whole the phase portrait near the w -axis looks like



Singular points $(\pi, 0)$ II

Consider domains (b) and (c) near the point. Let it be (c).

$$\dot{x} = y, \dot{y} = -k \left[\frac{1+a^2}{2} \sin^2 x + 2 \frac{1+a^3}{3} y \sin x + \frac{1+a^4}{4} y^2 \right] + k \frac{\sin^4 x}{6y^2}.$$

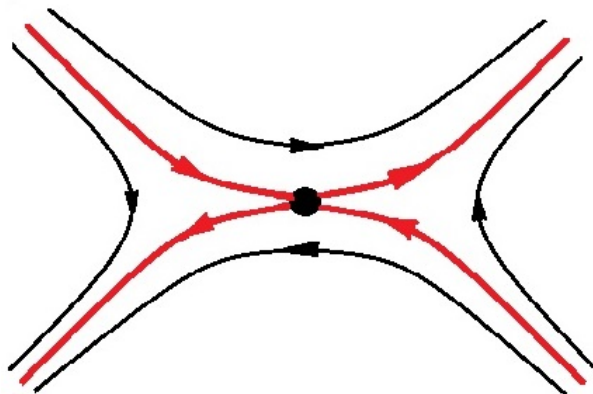
With $w, y = w \sin x$, $-1/a \leq w \leq -1$, and after the division of the second equation by $\sin x$ we get $\dot{x} = w \sin x$ and

$$\dot{w} = -w^2 \cos x - k \left[\frac{1+a^2}{2} + 2 \frac{1+a^3}{3} w + \frac{1+a^4}{4} w^2 \right] \sin x + k \frac{\sin x}{6w^2}.$$

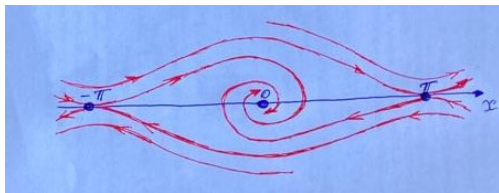
The last field is smooth near segment $\{x = \pi, -1/a \leq w \leq -1\}$. Hence for x sufficiently close to π the phase curves near the segment go up almost vertically

Singular points $(\pi, 0)$ III

Hence the singular point $(\pi, 0)$ is topologically saddle:



The full picture



Topologically it is the same like in V.I.Arnold's textbook.

$$\ddot{x} + a\dot{x} + kx = 0, \quad a > 0, \quad k > 0$$

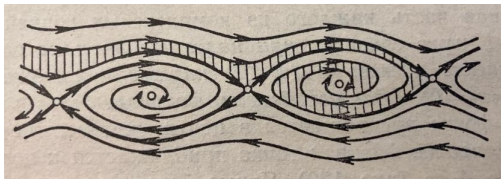
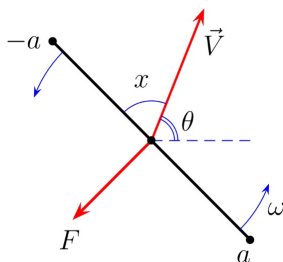


Figure: V.I.Arnold, Ordinary differential equations (various editions).

Flight of a rod



$$\begin{cases} \dot{v} = -\frac{2\rho}{m} \sin x \int_{-a}^a (r\omega + v \sin x) |r\omega + v \sin x| dr \\ \dot{x} = \omega - \frac{2\rho}{m} \frac{\cos x}{v} \int_{-a}^a (r\omega + v \sin x) |r\omega + v \sin x| dr \\ \dot{\omega} = -\frac{2\rho}{I} \int_{-a}^a (r\omega + v \sin x) |r\omega + v \sin x| r dr \end{cases}$$

Calculations are different in 3 cases when the sign of $r\omega + v \sin x$:

A) is either non-negative ($=A_+$) or non-positive ($=A_-$) for all $r \in (-a, a)$,

B) changes sign at $r_0 = -v \sin x / \omega \in (-a, a)$, from "-" to "+" ($=B_-$), or vice versa.

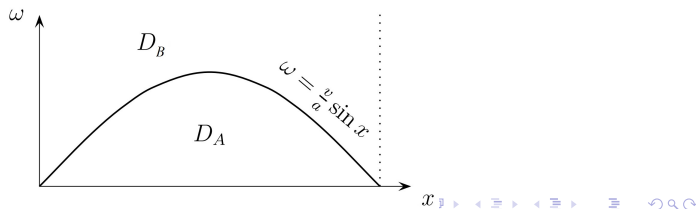
Model equations

$$(A_+) \quad \begin{cases} \dot{v} = -\frac{2\rho}{m} \sin x \left(\frac{2}{3} a^3 \omega^2 + 2av^2 \sin^2 x \right) \\ \dot{x} = \omega - \frac{2\rho}{m} \frac{\cos x}{v} \left(\frac{2}{3} a^3 \omega^2 + 2av^2 \sin^2 x \right) \\ \dot{\omega} = -\frac{8\rho a^3}{3I} v \omega \sin x. \end{cases},$$

$$(B_-) \quad \begin{cases} \dot{v} = -\frac{4v\rho}{m} \sin^2 x \left(\frac{v^2 \sin^2 x}{3\omega} + a^2 \omega \right) \\ \dot{x} = \omega - \frac{4\rho}{m} \cos x \sin x \left(\frac{v^2 \sin^2 x}{3\omega} + a^2 \omega \right) \\ \dot{\omega} = -\frac{2\rho}{I} \left[\frac{v^2 \sin^2 x}{\omega^2} \left(-\frac{1}{6} v^2 \sin^2 x + a^2 \omega^2 \right) + \frac{a^4 \omega^2}{2} \right] \end{cases}$$

Domain of study: $D := \{0 \leq x \leq \pi, 0 < v, 0 \leq \omega\} = D_{A+} \cup D_{B-}$.

Boundary: $a\omega = v \sin x, 0 \leq x \leq \pi, 0 \leq v$.



Stabilization I

Theorem

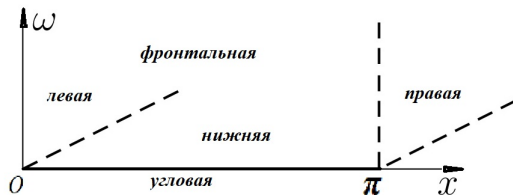
In the interior of the domain D , when moving, both ω and v decrease. In particular, the function $v + \omega$ decreases, and any trajectory of the model tends to the boundary of this domain.

The boundary of domain D is the union of its five parts:

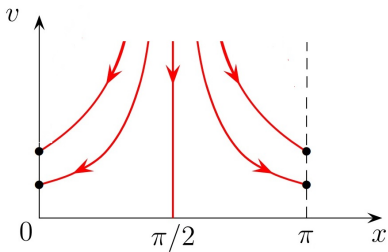
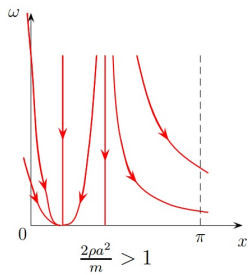
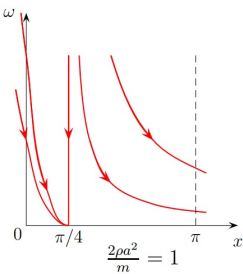
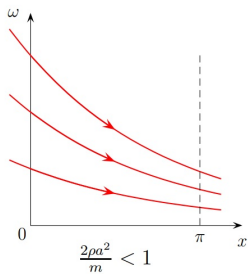
$left = \{x = 0, w > 0, v > 0\}$, $right = \{x = \pi, w > 0, v > 0\}$,

$bottom = \{x \in [0, \pi], w = 0, v > 0\}$, $front = \{x \in [0, \pi], w > 0, v = 0\}$

$corner = \{x \in [0, \pi], w = v = 0\}$.



Stabilization II



Some bibliography

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Thanks for the attention!